



Taming AI workloads in Apache Airflow

Dag patterns to avoid infrastructure instability



Jason(Zhe-You) Liu

Astronomer • github.com/jason810496 • linkedin.com/in/zhe-you-liu

Any workload that **outlives its Airflow task**.

Data processing

Spark, Flink, dbt Cloud

AI / ML

fine-tuning, batch
inference, training

Infrastructure

cluster provisioning,
EMR, Dataproc

The pattern is generic. **AI workloads** just make it expensive to get wrong.

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The problem

How a task actually runs, and why SIGTERM lies.

THE PROBLEM

TWO QUESTIONS

DEFER

THE CANCEL PATH

3.3

SUMMARY

A STORY YOU HAVE PROBABLY LIVED

Your GPU job didn't fail. Airflow killed it.

THE JOB

8× H100 fine-tune
14 hours planned · ~\$30/hr

HOUR 11

Worker pod evicted.
Not the training job — the *watcher*.

THE RESULT

operator.on_kill fired. Job cancelled.
~\$330 burned. Next run starts at zero.

Representative scenario, illustrative numbers — not a specific customer.

A task instance **pushes** its own liveness.

WORKER POD



Push-based. Airflow never asks the task how it is doing. **Silence is interpreted as death.**

What **operator.on_kill** usually contains.

finetune_operator.py

the shape everyone ships

```
class SubmitJobOperator(BaseOperator):

    def execute(self, context):
        self.job_id = client.submit(self.spec)
        client.wait_for_completion(self.job_id)

    def on_kill(self):
        client.cancel(self.job_id)    # ← this line
```

One line. Nobody would review it and object. The defect is in **what calls it**.

FOUR CAUSES. ONE SIGNAL.

ALL FOUR PATHS VERIFIED IN SUPERVISOR.PY

Mark Failed or clear

404 / 409 / 410

API server unreachable

3 failed heartbeats

k8s drain or evict

SIGTERM from outside

Preemption by the engine

job moves under you



operator.on_kill()

no reason · no flag · no ask

Only **Mark Failed / clear** wants the job dead.

Default: **15 seconds** of API-server silence is enough.

AIRFLOW CANNOT TELL THE DIFFERENCE.

If you cancel: false kills

A drain, or a 15-second network blip, murders a healthy 11-hour job.

If you don't: leaked jobs

"Mark Failed" leaves \$30/hr running until somebody notices.

Neither is a bug. The information needed to choose correctly never reaches the operator.

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Two questions

Can the watcher dodge `operator.on_kill`'s blind spot — and still stop the job on purpose?

THE PROBLEM

TWO QUESTIONS

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SUMMARY

QUESTION ONE

Can the watcher dodge **operator.on_kill**?

What has to change is what's listening for SIGTERM in the first place.

QUESTION TWO

Then how do we **explicitly stop** the job?

Something else has to carry the "the user wants this dead" signal.

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Defer

Where the watch belongs, and why.

THE PROBLEM

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SUMMARY

Operator vs trigger: two different runtimes.

Operator runs in a `subprocess` on a Worker

`execute()`
blocks for hours
supervised, heartbeated

`operator.on_kill()`
fires on any SIGTERM
no reason attached

`self.defer()`

|



Trigger runs as an `async coroutine` on a Triggerer

rebuilt from no subprocess

(classpath, kwargs) `operator.on_kill()` is unreachable

Inside the trigger.

__INIT__ · 1 / 4

finetune_trigger.py

the constructor

```
class WatchJob(BaseTrigger):  
  
    def __init__(self, job_id: str):  
        self.job_id = job_id        # the whole state there is
```

No `execute()`, no operator, no task context — only **constructor arguments**.

The serialized tuple is the **recovery snapshot**.

SERIALIZE() · 2 / 4

finetune_trigger.py

what crosses the process boundary

```
class WatchJob(BaseTrigger):  
  
    def serialize(self) -> tuple:  
        return "finetune_trigger.WatchJob", {"job_id": self.job_id}  
           # classpath                        kwargs
```

The **only** thing that survives a rebuild. Anything else is gone after a restart.

Inside the trigger.

RUN() · 3 / 4

finetune_trigger.py

the watch loop

```
class WatchJob(BaseTrigger):  
  
    async def run(self):  
        while True:  
            status = await check(self.job_id)  
            if status.is_terminal():  
                yield TriggerEvent({"status": status})  
                return  
            await asyncio.sleep(30)
```

An **async generator**. This poll costs a coroutine, not a worker slot.

The operator hands off to it.

EXECUTE() · 4 / 4

finetune_operator.py

calling the trigger

```
class SubmitJobOperator(BaseOperator):

    def execute(self, context):
        job_id = client.submit(self.spec)
        self.defer(trigger=WatchJob(job_id=job_id), method_name="complete")

    def complete(self, context, event):
        return event["status"]
```

One call, right after submit. Everything from here happens **without this operator's process**.

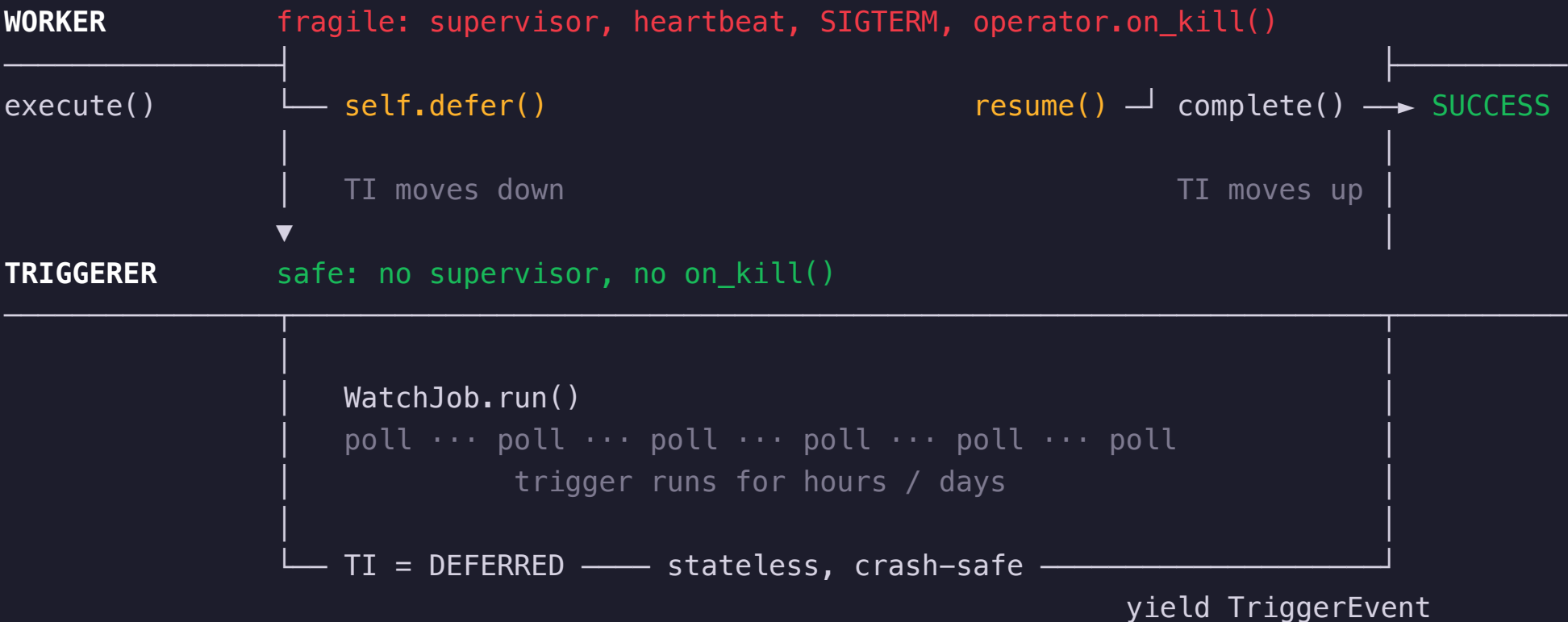
What **defer** actually does.

WORKER

```
execute() —submit→ remote job now RUNNING $30/hr
|
└ self.defer(trigger=WatchJob(job_id))
    |
    ├── serialize() → (classpath, kwargs) → trigger table
    └ task subprocess ends                TI = DEFERRED
```

the serialized snapshot is all that remains

Where the task instance **lives** at each phase.



The triggerer is **stateless** and crash-safe.

THE COROUTINE IS STATELESS. RECOVERING COSTS NOTHING TO LOSE.

TRIGGERER A

WatchJob.run()
polling the job

x SIGTERM (deploy/drain/OOM)
coroutine cancelled

TRIGGER TABLE

(classpath, kwargs)
the **serialized snapshot**

snapshot **SURVIVES**
TI still **DEFERRED**

TRIGGERER B

WatchJob(**kwargs)
rebuilt from the snapshot

poll

still running

still **RUNNING**, started 11h ago

RAY JOB

running on GPU
no idea Airflow
exists

THE CENTRE OF THE TALK

The task instance **never left DEFERRED.**

It did not fail. It did not retry. **operator.on_kill** never fired.

An entire Airflow component died and the Dag did not notice.

A trigger is already a watcher. The statelessness this pattern needs is not a discipline you impose — it is a ***precondition the runtime enforces.***

QUESTION ONE – ANSWERED

Can the watcher dodge **operator.on_kill**?

Yes. Defer moves the TI to the triggerer. No subprocess, no SIGTERM, no on_kill.

QUESTION TWO – STILL OPEN

Then how do we **explicitly stop** the job?

The watcher is safe, but we lost the cancel path entirely. Something else has to carry the **"the user wants this dead"** signal.

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The cancel path

Submit, watch, cancel — and a @teardown that carries intent.

THE PROBLEM

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SUMMARY

SUBMIT. WATCH. CANCEL.



Three tasks because they have three different **failure semantics**. Retrying **watch** must be free, retrying **submit** must be a no-op, **cancel** must fire on intent and nothing else.

Use **@teardown** as the cancel.

Airflow docs

setup & teardown howto

```
create_cluster >> run_query >> delete_cluster.as_teardown(setups=create_cluster)
```

dags/finetune_dag.py

our nouns

```
submit >> watch >> cancel.as_teardown(setups=submit)
```

Your remote AI job is the cluster. Three operators, one **@teardown**, since 2.7.

Why @teardown discriminates correctly.

EVENT	WATCH REACHES	TEARDOWN FIRES?	REMOTE JOB
triggerer redeployed	DEFERRED	no	LIVES ✓
API server blip → SIGTERM	DEFERRED	no	LIVES ✓
worker evicted (task deferred)	DEFERRED	no	LIVES ✓
user clicks "Mark Failed"	FAILED	YES	cancelled ✓
user marks Dag run failed	FAILED	YES	cancelled ✓
job genuinely fails	FAILED	YES	no-op ✓
job succeeds	SUCCESS	YES	no-op ✓

A signal handler fires on process events. A teardown fires on task-state events.

Only task state carries intent.

Start from the anti-pattern.

BUILDING THE PATTERN · 1 / 5

finetune_operator.py

before

```
class SubmitJobOperator(BaseOperator):  
  
    def execute(self, context):  
        self.job_id = client.submit(self.spec)  
        client.wait_for_completion(self.job_id)  
  
    def on_kill(self):  
        client.cancel(self.job_id)    # ← the line everyone ships
```

One operator. One process. One hook deciding life or death.

Make the **watch** deferrable.

BUILDING THE PATTERN · 2 / 5

finetune_operator.py

building the pattern

```
class SubmitJobOperator(BaseOperator):

    def execute(self, context):
        job_id = client.submit(self.spec)
        self.defer(trigger=WatchJob(job_id=job_id), method_name="complete")

    def on_kill(self):
        client.cancel(self.job_id)      # ← unreachable while DEFERRED
```

The subprocess exits between polls, so the hook has no process to fire in.
This step buys **kill discrimination**, not the worker slot everyone assumes.

Add the `@teardown` for cancellation.

BUILDING THE PATTERN · 3 / 5

dags/finetune_dag.py

building the pattern

```
submit = SubmitJob(
    task_id="submit",
    job_name=name,
    spec=spec,
    deferrable=True,
    wait_for_termination=True,
).as_setup()
cancel = CancelJob(task_id="cancel", job_name=name)

submit >> cancel.as_teardown(setups=submit)
```

Cancellation gets a home. `as_teardown()` fires on **task state**, not signals.

End the task **in** the trigger.

END_FROM_TRIGGER=TRUE · AIRFLOW.TRIGGERS.BASE · AIRFLOW 2.10+

finetune_trigger.py

how the watch hands back

```
async def run(self):
    status = await watch(self.job_id)

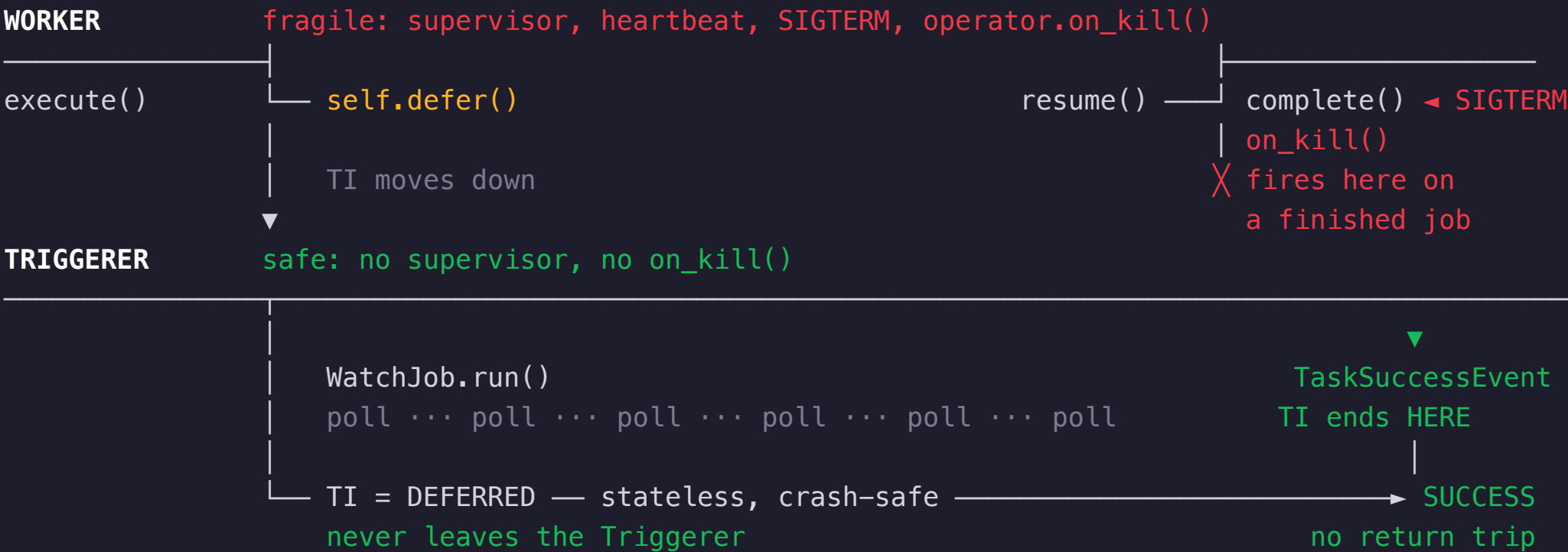
    if self.end_from_trigger:
        yield TaskSuccessEvent()           # ends here
    else:
        yield TriggerEvent({"status": status}) # goes back to a worker
```

TriggerEvent → worker resumes → operator.complete() → SUCCESS
x a fresh subprocess: supervisor · heartbeat · SIGTERM
x operator.on_kill is reachable again in this window

TaskSuccessEvent → the triggerer sets the final state → SUCCESS
✓ no worker, no subprocess, no hook that can fire

Skip the last mile entirely.

END_FROM_TRIGGER=TRUE ELIMINATES THE RETURN TRIP TO THE WORKER



Group the three into one unit.

dags/finetune_dag.py

building the pattern

```
with TaskGroup(group_id=group_id) as g:
    name = deterministic_name(group_id)

    submit = SubmitJob(
        task_id="submit",
        job_name=name,
        spec=spec,
        deferrable=True,
        wait_for_termination=True,
    ).as_setup()
    cancel = CancelJob(task_id="cancel", job_name=name)

    submit >> cancel.as_teardown(setups=submit)
```

One **group_id** in, one deterministic name computed once, shared by all three tasks.

The factory. 2.7 through 3.2 – and after.

BUILDING THE PATTERN · 5 / 5

dags/finetune_dag.py

building the pattern

```
def resilient_ai_job(*, group_id, spec):
    with TaskGroup(group_id=group_id) as g:
        name = deterministic_name(group_id)

        submit = SubmitJob(
            task_id="submit",
            job_name=name,
            spec=spec,
            deferrable=True,
            wait_for_termination=True,
        ).as_setup()
        cancel = CancelJob(task_id="cancel", job_name=name)

        submit >> cancel.as_teardown(setups=submit)
    return g
```

dags/finetune_dag.py

usage

```
resilient_ai_job(group_id="finetune", spec=FINETUNE) >> evaluate
```

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3.3 collapses it all

One operator, one trigger, `trigger.on_kill` does the rest.

THE PROBLEM

TWO QUESTIONS

DEFER

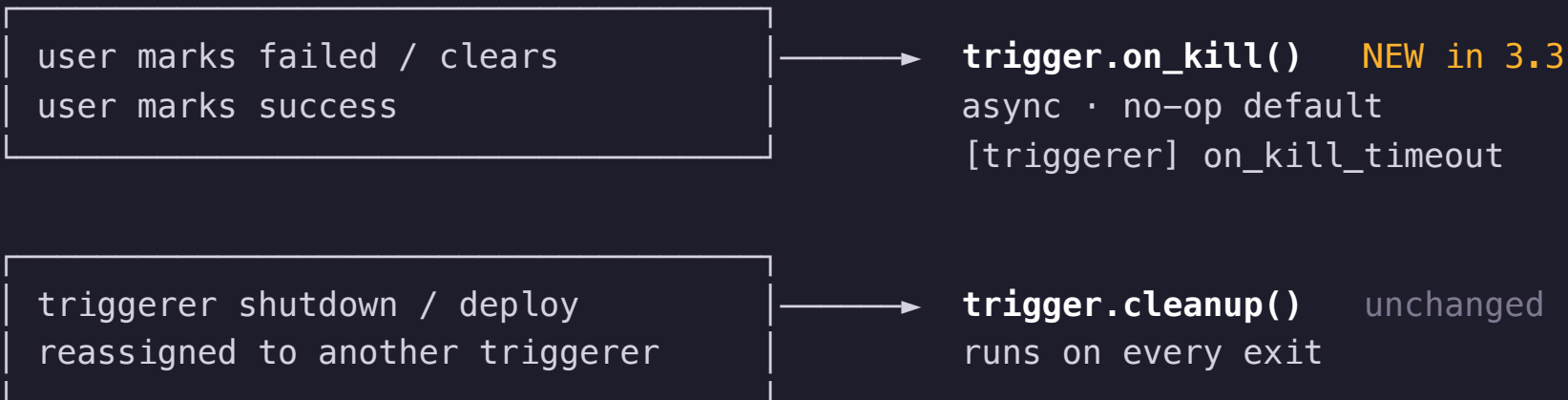
THE CANCEL PATH

3.3

SUMMARY

3.3.0 introduces the **trigger.on_kill** hook.

PR #65590 · MILESTONE 3.3.0



The trigger itself can now tell a real kill from infrastructure noise.
So **submit**, **watch** and **cancel** collapse into **one operator call**.

Authoring the whole pattern in one operator, since 3.3.0.

WALKING THE INTERNALS · 1 / 3

ONLY WHEN THE PROVIDER'S TRIGGER IMPLEMENTS TRIGGER.ON_KILL

dags/finetune_dag.py

the whole task

```
SubmitJob(  
    task_id="finetune",  
    job_name=DETERMINISTIC_NAME,  
    deferrable=True,  
    wait_for_termination=True,  
)
```

- All a Dag author writes. Nobody wrote a `CancelJob` task.
- An **explicit kill** — Mark Failed, clear, mark success — is handled inside the provider's trigger by `trigger.on_kill()`.

Inside execute().

WALKING THE INTERNALS · 2 / 3

finetune_operator.py

shipped by the provider

```
class SubmitJobOperator(BaseOperator):  
  
    def execute(self, context):  
        job_id = client.submit(self.spec)  
        self.defer(trigger=WatchJob(job_id=job_id))
```

No `method_name`, no `complete()` — the trigger ends the task directly.

Inside the trigger, both hooks.

WALKING THE INTERNALS · 3 / 3

finetune_trigger.py

shipped by the provider

```
class WatchJob(BaseTrigger):

    def __init__(self, job_id, *, end_from_trigger=True):
        ...

    async def run(self):
        while True:
            status = await check(self.job_id)
            if status.is_terminal():
                if self.end_from_trigger:
                    yield TaskSuccessEvent()
                else:
                    yield TriggerEvent({"status": status})
            return
            await asyncio.sleep(30)

    async def on_kill(self) -> None:
        await self.client.stop_job(self.job_id)
```

trigger.cleanup() vs trigger.on_kill().

RECAP – EVERY TRIGGER EXIT, MAPPED TO THE HOOK IT ACTUALLY REACHES

trigger.cleanup()

- triggerer shutdown or deploy
- reassigned to another triggerer

trigger.on_kill() 3.3+

- user marks failed / clears

THE HONEST CONCESSION THAT EARNS THE CONCLUSION

trigger.on_kill() is the **only** place where
infrastructure instability and **user-intended kill**
are distinguishable.

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Summary

2.7 to 3.0, 3.0 to 3.2, 3.3!

THE PROBLEM

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SUMMARY

Every version since 2.7 can do this. Newer versions need less code.

VERSION	IDENTITY	WATCH	USER-KILL
2.7 – 3.0	deterministic name	deferrable	teardown task
3.0 – 3.2	deterministic name + trigger_kwargs	deferrable	teardown task
3.3!	deterministic name + task_state_store (AIP-103)	deferrable	teardown + trigger.on_kill()

Every trick, and where you can use it.

FINAL SUMMARY – THE LAST TWO ROWS ARE THE ONLY ONES NEEDING A RECENT AIRFLOW

TRICK	WHAT IT BUYS	WHERE
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deterministic job name	every attempt re-finds the same job	any
AlreadyExists = success	submit is a safe no-op on retry	any
deferrable=True	no subprocess for SIGTERM to reach	2.2+
cancel.as_teardown(setups=submit)	cancel fires on task state, not signals	2.7+
wait_for_termination=True	submit + watch collapse into one task	provider
end_from_trigger=True	no resume, so no on_kill at completion	2.10+
trigger.on_kill()	prompt cancel on real user intent	3.3.0

Questions?

- SIGTERM carries no reason, so `operator.on_kill` cannot carry a decision.
- A signal handler fires on process events. A teardown fires on task-state events.
- The triggerer is the only place those two are distinguishable.

Jason(Zhe-You) Liu • Astronomer

jason.liu@astronomer.io

github.com/jason810496

linkedin.com/in/zhe-you-liu